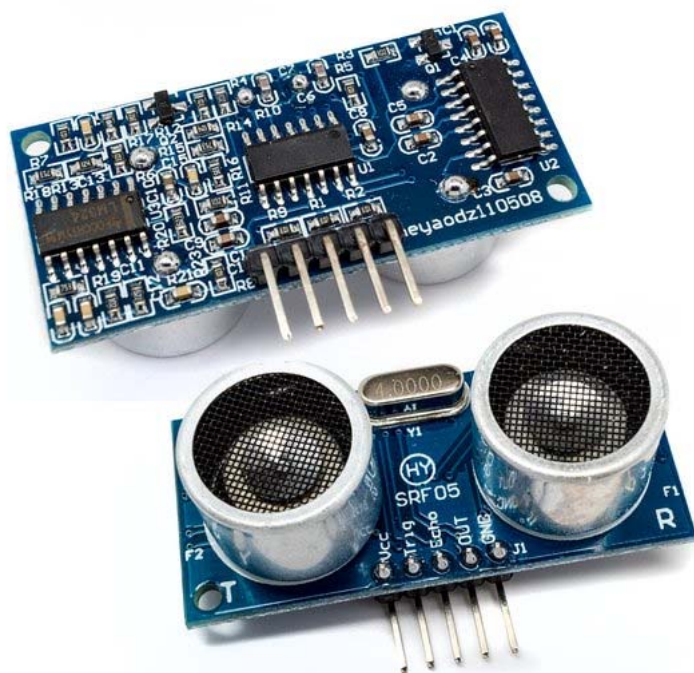


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HC-SR05 / HY-SRF05 Precision Ultrasonic Sensor

Designed by Upgrade Industries(/stores/upgradeindustries/)



(https://d3s5r33r268y59.cloudfront.net/5132/products/thumbs/2014-03-04T15:41:23.991Z-hcsr05.jpg.2560x2560_q85.jpg)



\$6.99

(30,38 lei RON)

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Description Shipping

An ultrasonic ranging sensor with slightly better accuracy.

Ultrasonic sensors overcome many of the weaknesses of IR sensors - they provide distance measurement regardless of color and lighting of obstacles.

They also provide lower minimum distances and wider angles of detection to guarantee that obstacles are not missed by a narrow sensor beam.

THIS particular model is an upgrade from the lower precision HC-SRO4. This has 5 pins and can be used in 1-pin trigger/echo or 2-pin.

Specifications

Check the datasheet for details and graphs but these are the highlights:

- **Trigger Pin Format:** 10 μ s digital pulse
- **Sound Frequency:** 40 kHz
- **Echo Pin Output:** 0-V_{CC}
- **Echo Pin Format:** output is DIGITAL and directly proportional with range. See our conversion formula above.
- **Measurement Range:** 2cm to ~4.5m
- **Measurement Resolution:** 0.3cm
- **Measurement Angle:** up to 15 deg
- **Measurement Rate:** 40 Hz
- **Supply Voltage:** 4.5V to 5.5V
- **Supply Current:** 10 to 40mA
- **Connector:** standard 5-pin male connector which can plug directly into breadboards.

Measurement Procedure & Formula

Distance measurements can be made with microcontrollers in a straightforward manner:

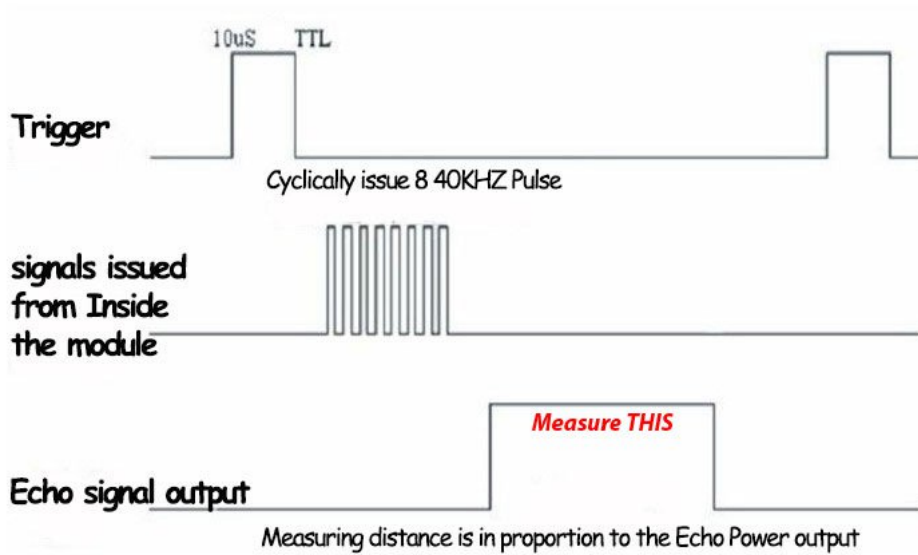
You can find an Arduino Library with code here: <http://forum.arduino.cc/index.php?topic=106043.0>(<http://forum.arduino.cc/index.php?topic=106043.0>)

- Send a 10 μ s wide pulse to the sensor on the Trigger Pin. The sensor will automatically send out a 40 kHz wave.
- Begin monitoring the output from the Echo Pin and
- When the Echo Pin goes high, begin a timer.
- When the Echo Pin goes low, record the elapsed time from the timer and use the following conversion formula:

$$\text{Distance (in cm)} = (\text{elapsed time} * \text{sound velocity (340 m/s)}) / 100 / 2$$






Note: we divide distance by 2 because the sensor returns the round trip time, which doubles the distance measurement.

Ultrasonic Timing Diagram



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